first class demo

```
python is slow
import numpy as np
def f(x, y, z):
  return np.exp(-x**2-y**2-z**2)
def main():
    N = 500
    xv = np.linspace(0.0, 2.0, N)
    dx = xv[2] - xv[1]
    ans = 0.0
    for x1 in xv:
        for x2 in xv:
            for x3 in xv:
                ans += f(x1, x2, x3) * dx**3
    print(ans)
    return ans
main()
VS
function f(x, y, z)
    ret1 = exp(-x^2-y^2-z^2)
    return ret1
end
function main()
    N = 500
    xv = range(0.0, 2.0, length=N)
    dx = xv[2] - xv[1]
    ret = 0.0
    for x1 in xv, x2 in xv, x3 in xv
        ret += \exp(-x1^2-x2^2-x3^2) * dx^3
    end
    print(ret)
    return ret
end
```

main()

The output:

```
time julia test2.jl
0.6910931690128204
Executed in 937.50 millis fish external
  usr time1.88 secs0.22 millis1.88 secssys time0.89 secs1.03 millis0.89 secs
time python3 test2.py
0.6910931690128224
        _____
                ------
Executed in 80.36 secs fish external
  usr time 81.11 secs 221.00 micros 81.11 secs
  sys time 1.24 secs 971.00 micros 1.24 secs
side effects
xarr = [1, 2, 3]
yarr = [2, 4, 6]
a = xarr
a += yarr
```

In python (but **not** in Julia), this would have modified xarr. But matrix side effect is still there:

Amat = [1 2 3; 4 5 6] Bmat = Amat Bmat[:,1] = [7 11]

what would Bmat be? What happens to Amat?

logistic curve

see class notes